Motion to meet the highest demands



Electromechanics made by Parker **Product overview**



Product overview Electromechanics



Visualisation __4

- Systems for Control & Monitoring
- Touch Screens
- Software for Windows®-based HMI

Motion control __5

- Controllers for high-technology applications
- PLC based Motion Control Systems
- Digital and analogue peripheral modules

Drive technology __7

- AC servo drives for centralised and decentralised automation
- DC servo drives
- Stepper motor drives

Interfaces for automation:

- +/-10V or Step/Direction
- Digital Inputs & Outputs
- RS232 / RS485
- **■** Profibus
- CANopen
- SERCOS
- DeviceNet
- PowerLink

Feedback systems:

- Tacho generator
- Resolver
- Encoder
- Sinus/Cosinus
- SinCos® Hiperface
- EnDat®
- Analogue Hall
- Distance coded



- Servo motors
- Stepper motors
- Linear servo motor kits
- Torque motor kits
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- **■** Economy
- **■** Precision

Planetary gearboxes __11



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- Linear actuators
- Vertical actuators
- Electric cylinder
- Linear motor actuators (PowerRod)

■ Precision actuators & tables __14

- Linear actuators
- Tables (X-Y and rotary)
- Miniature tables
- Stacking tables



Control & Monitoring (Visualisation)

Parker's components for control, monitoring and user interfacing are suitable for a wide range of applications. They range from simple, cost-efficient two-line displays to colour touch screens. Modern, Windows® based software tools support the user in application programming as well as integration of the components into machine and company networks.

Pop series

| Pop technical data (summary) | | | | | | | |
|------------------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | Pop 11 | Pop 12 | Pop 21 | Pop 22 | Pop 23 | Pop 31 | Pop 32 |
| | | | | | | | |
| Display | mono | mono | mono | mono | mono | mono | colour |
| | text | graphic | graphic | graphic | graphic | 5.6" | 5.6" |
| | | | | | | diagonal | diagonal |
| Size | 2 lines | 4 lines | 4 lines | 4 lines | 8 lines | 16 lines | 16 lines |
| | 20 characters | 20 characters | 20 characters | 20 characters | 40 characters | 40 characters | 40 characters |
| Function keys | 4 | 4 | 12 | 12 | 23 | Touch | Touch |
| LED | 5 | 5 | 13 | 13 | 24 | - | - |
| Multi-lingual projects | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| Fieldbus option | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| RS232, RS422 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| RS485, CL 20mA | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| Printer interface | - | - | - | - | ✓ | ✓ | ✓ |
| User program | 512 kB | 8 MB | 8 MB |
| Memory expansion | - | - | 512 kB | 512 kB | 512 kB | - | - |
| Recipe memory | - | - | - | 32 kB | 16 kB | 32 kB | 32 kB |
| Downloadable font | - | ✓ | ✓ | ✓ | ✓ | - | - |
| Numeric keypad | - | - | ✓ | ✓ | ✓ | Touch | Touch |
| Real time clock, battery | - | - | - | ✓ | √ | ✓ | ✓ |
| Event list for alarms | - | - | - | ✓ | ✓ | ✓ | ✓ |
| Screen saver | - | - | - | - | - | ✓ | ✓ |







Pop 2



Pop 2



Pop 32



Interact/InteractXTM series

The Interact/InteractX[™] software package was developed for the visualisation (control & moninitoring) of complete machines and process plants. Interact features a very simple interface and extensive graphics elements. The package includes a number of software modules for recipe management, trend analysis etc. We offer an extensive package of drivers for almost all PLC systems. Interact was especially designed for cost-efficient, embedded hardware platforms.

Parker offers touch screens in 6", 10", 12" and 15" sizes.

Software functions include:

- Exceptionally realistic 3D graphic elements (Panel Tools)
- Freely configurable graphic elements
- Alarm functions
- OPC Client/OPC Server
- Active-X[™] support
- Visual Basic® for application software
- Multi-lingual projects
- Communication interfaces for system integration
- Compatible with the 21CFR11 standard

Motion controls

Parker Hannifin offers advanced and extremely powerful platforms for the control of complex, multi-axis motion sequences.

ACR Controllers

ACR controllers are powerful motion controllers designed to perform complex tasks. The controllers can perform multiple tasks simultaneously, and typically up to 24 programs can be processed in parallel. The product incorporates powerful functions such as batch compensation, electronic cam generation, fast trigger inputs, 3D-contour movements and tangential axes. In addition, Visual Basic® and C++ libraries are available for the user.





| ACK controller technical data (summary) | |
|---|---|
| | ACR9000 |
| Number of axes (Servo, Stepper) | 1 to 8 |
| CPU Performance | 150MFLOPS |
| Digital I/Os | 24/48 |
| | can be extended to 1024 via CANopen and PIO |

C3 powerPLmC

C3 powerPLmC is a new automation platform for combined PLC, Motion Control and visualisation tasks. The C3 powerPLmC control system is based on internationally recognised standards in programming, communication and interfacing. Programming follows the IEC61131-3 standard, and the powerful platform executes 1000 IL instructions in less than 100µs. This makes the C3 powerPLmC one of the fastest and most powerful PLCs for motion control tasks.

I/O voltage

The standard Ethernet interface included with the package forms the basis for the state-of-the-art remote diagnostics via the Internet or Intranet. Parker has integrated an OPC Interface into the control system for connecting open Windows-based process visualisation and supervisory systems.

The Drive Interface guarantees the simple integration of Parker Hannifin's Compax3 Servo Controllers into Machines Automation Structures without detailed knowledge about Field Bus Systems. **Your advantage:** Time- and cost-saving.



Compax3 powerPLmC-C1



C3 powerPLmC-E2x

| | | Compax3 powerPLmC-C1x | C3 powerPLmC-E2x |
|-----------------------|--|----------------------------------|----------------------------------|
| | | (with integrated axis) | (standalone) |
| General information | Platform | 32 Bit RISC, 200 MHz | 32 Bit RISC, 200 MHz |
| | Boot Flash/Program memory FLASH | 1 Mbyte/4 Mbyte | 64 MB Compact Flash |
| | Data memory SDRAM/Data memory non volatile | 16 Mbyte/32 kByte NVRAM | 16 Mbyte/32 kByte NVRAM |
| | Real time clock | Yes, battery backed | Yes, battery backed |
| | Operating system/supply | Real-time multitasking / 24 V DC | Real-time multitasking / 24 V DC |
| | Servo extention | Compax3 - axis | - |
| Controller features | Processing time | < 100 μs/1000 IL lines | < 100 μs/1000 IL lines |
| Programming/Debugging | Programming system | CoDeSys | CoDeSys |
| | Programming languages | IL, KOP, FUP, ST, AS, CFC | IL, KOP, FUP, ST, AS, CFC |
| Protocol | | IEC61131-3, PLCopen | IEC61131-3, PLCopen |
| | Program interface | Fast Ethernet | Fast Ethernet |
| /isualisation | Local/OPC Server | yes/yes | yes/yes |
| nterfaces | Fieldbusses (standard) | CANopen, Ethernet 10/100 | 2*CANopen, Ethernet 10/100 |
| | Fieldbusses (option) | Profibus DP Slave | Profibus DP Slave |
| | Serial interfaces | - | 2*RS232/2*RS232/RS422/RS485 |
| | Digital I/Os | PIO External terminals | PIO External terminals |



Peripheral modules – PIO digital and analogue inputs/outputs

Parker Hannifin's PIO modular bus terminal system uses the associated sensors to record a wide variety of control signals from field devices. Connections to the field level can be implemented quickly and reliably with PIO.

- Fieldbus-independent design using fieldbus couplers
 - **■** Profibus
 - **■** CANopen
 - **■** DeviceNet
- Easy to extend by replacing modules
- Exceptionally compact design
- Intrinsically-safe contacting
- Different voltages can be combined







PIO-430





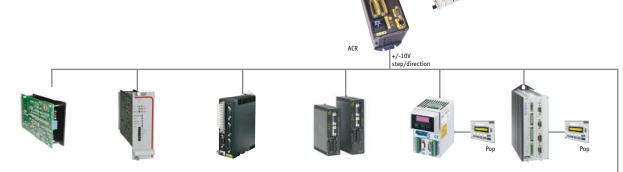
PIO technical data (summary)

| | Digital Inputs | Analogue Inputs | Digital Outputs | Analogue Outputs |
|----------------|--------------------|--------------------|---------------------|---------------------|
| | PIO-400 | PIO-456 | PIO-501 | PIO-550 |
| | PIO-402 | PIO-468 | PIO-504 | PIO-552 |
| | PIO-430 | PIO-480 | PIO-530 | PIO-556 |
| Number of I/Os | 2/4/8 | 4/2 | 2/4/8 | 2/2 |
| Data width | 2/4/8 Bit | 4*2/2*2 Byte | - | - |
| Connection | 2 - 4 wire | single ended | short-circuit proof | short-circuit proof |
| | 2 - 3 wire | differential input | positive switching | positive switching |
| | single wire | 12/14 Bit | | 12 Bit |
| | positive switching | +/-10V | | +/-10V |
| Signal | DC-3V to +5V | 0V to 10V | 0.5 A | 0V to 10V |
| | DC 15V to 30V | 0mA to 20mA | | 0mA to 20mA |
| Dimensions | 12 x 64 x 100 | 12 x 64 x 100 | 12 x 64 x 100 | 12 x 64 x 100 |

Drive technology

Parker Hannifin's drives are based on integrated digital technology. This is a prerequisite for higher power density of the stepper and servo motor drives. The outstanding features of small dimensions, high functionality and standardised interfaces simplify the integration into machines and process plant.

Drive systems for high-technology applications



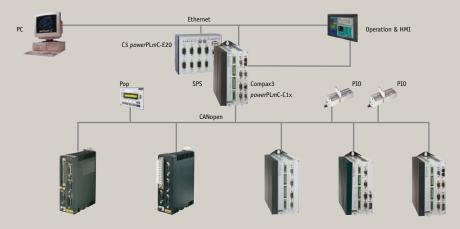
| Centralised controller structure | | | | | | |
|----------------------------------|------------------------|-----------------------|---------------|-------------|---------------|------------------------|
| Servo drive data | TRM | TBF/TBL | ViX Servo | Aries | sLVD | Compax3 I10T10 |
| Cunnly valtage | 24/54VAC | 60/120/250VAC | 24 – 80VDC | 120/240VAC | 240VAC | 240/480VAC |
| Supply voltage | , | 00/120/250VAC | 24 - 8UVDC | 120/240VAC | 240VAC | 240/480VAC |
| | or 34/76VDC | | | | | . /- |
| Phases | | 1 | DC Bus | 1 | 3 | 1/3 |
| Output current ratings | 7/15A (24VAC) | 5/10A (60VAC) | 2.5/7.5A | 1.0/3.0A | 1.25/2.5A | 2.5/5.0A (1AC230V) |
| (continous/peak) | 5/15A (54VAC) | 10/25A (60VAC) | 5.0/15A | 1.75/5.25A | 2.5/5.0A | 6.3/12.6A (1AC230V) |
| | 8/20A (54VAC) | 7/18A (120VAC) | | 3.0/9.0A | 5.0/10.0A | 10/20A (3AC230V) |
| | | 2.5/5A (120VAC) | | 4.5/13.5A | 7.0/14.0A | 15/30A (3AC230V) |
| | | 10/20A (120VAC) | | 6.3/14.2A | | 1.5/4.5A (3AC400V) |
| | | 15/30A (120VAC) | | | | 3.8/9.0A (3AC400V) |
| | | 10/20A (250VAC) | | | | 7.5/15.0A (3AC400V) |
| | | | | | | 15.0/30.0A (3AC400V) |
| | | | | | | 30.0/60.0A (3AC400V) |
| Feedback | Tacho generator | Resolver | Encoder | Encoder | Resolver | Resolver/Encoder, |
| | | Encoder | Resolver | | | Sine/Cosine, SinCos®, |
| | | | SinCos® | | | EnDat®, Analogue Hall, |
| | | | | | | Distance coded |
| Command interface | +/-10V | +/-10V | +/-10V | +/-10V | +/-10V | +/-10V |
| | | | 5 V S/R | 5 V S/R | 5 V S/R | 5 V S/R; 24 V S/R |
| Integrated digital I/O | - | - | 5/3 | - | 3/2 | 4/4 |
| Integrated analogue I/O | - | - | - | - | - | 2/2 |
| System structure | centralised | centralised | centralised | centralised | centralised | centralised |
| | | | decentralised | | decentralised | decentralised |
| Special features | DC – servo controllers | 19" Rack | | | | Safety technology on |
| | in 19" Rack | suitable for external | | | | board (safe standstill |
| | | Commutation | | | | according to EN954-1) |

The servo drives for high-technology applications are complemented by powerful stepper motor drives.

| Stepper motor drives technical data (summary) | | |
|---|---------------------|---------------------|
| | XL | ViX Stepper |
| Supply voltage | 24/48/80VDC | 24/48/80VDC |
| AC phases or DC bus | DC Bus | DC Bus |
| Rated output current (continuous) | 1.8A RMS | 2.8A RMS |
| | 3.5A RMS | 5.6A RMS |
| | 5.6A RMS | |
| Command interface | S/R | S/R |
| | Differential TTL | Differential TTL |
| System structure | centralised | centralised |
| | decentralised | decentralised |
| Special features | Ministep power step | Ministep power step |



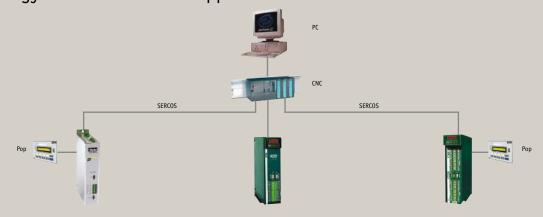
Drive technology for PLC controlled applications



| Decentralized | controllers | structure |
|---------------|-------------|-----------|

| Decentralized controllers structure | | | |
|-------------------------------------|----------------------------|----------------------------|---|
| | ViX Stepper | ViX Servo | Compax3 T11, Compax3 T30, Compax3 T40 |
| Supply voltage | 24 80VDC | 24 80VDC | 240/480VAC |
| Phases | DC Bus | DC Bus | 1/3 |
| Output current ratings | 2.8; 5.6 | 2.5/7.5A; 5/15A | (1AC230V): 2.5/5.0A; 6.3/12.6A |
| (continuous/peak) | | | (3AC230V): 10/20A; 15/30A |
| | | | (3AC400V): 1.5/4.5A; 3.8/9.0A; 7.5/15.0A; 15.0/30.0A; 30.0/60.0A |
| Feedback | Encoder | Encoder, Resolver, SinCos® | Resolver, Encoder, Sine/Cosine, SinCos®, EnDat®, Analogue Hall, distance-coded |
| Command interface | 5 V S/R | +/-10V, 5 V S/R | Encoder, Fieldbusses, digital I/O, Real-time bus |
| Fieldbus (option) | CANopen | CANopen | CANopen, Profibus DP, DeviceNet, PowerLink |
| Decentralised technology functions | Mark synchronisation | Mark synchronisation | Mark synchronisation, electronic gearbox, electronic cam generation (Compax3 T40) |
| Decentralised programming | EASI-Code | EASI-Code | Positioning sets (Compax3 T11), IEC61131-3, PLCopen (Compax3 T30, T40) |
| Integrated digital I/Os | 5/3 | 5/3 | 8/4 + 12 |
| Integrated analogue I/O | - | - | 2/2 |
| System structure | Centralised, decentralised | Centralised, decentralised | Centralised, decentralised |
| Special features | Microstep motor drive | | Safety technology on board (safe standstill according to EN954-1) |
| | | | |

Drive technology for CNC controlled applications



| Technical | data | (summary) |
|-----------|------|-----------|
| | | |

| recimient data (summary) | | | |
|------------------------------------|--|------------------------------------|---------------------------------|
| | HiDrive | SPD | TWIN/SPD |
| Supply voltage | 230 480VAC | 380 480VAC | 380 480VAC |
| Phases | 3 | 3 | 3 |
| Output current ratings | 2/4A; 5/10A; 8/16A; 16/32A; | 2/4A; 5/10A; 8/16A; 16/32A; 25/50A | 2/4A; 5/10A; 8/16A; |
| | 25/50A; 50/100A; 100/200A | | 16/32A; 25/50A |
| Feedback | Resolver, SinCos, Sincos & EnDat (single | e & multiturn) Encoder* | |
| Command interface / fieldbus | SERCOS | | |
| Decentralised technology functions | Electronic gearbox, electronic cam | | |
| Decentralised programming | Pico PLC (simple movements) | Pico PLC (simple movements) | Pico PLC (simple movements) |
| Integrated digital I/O | 4/2 | 4/2 | 4/2 |
| Integrated analogue I/O | 2/2 | 2/1 | 2/1 |
| System structure | centralised, decentralised | centralised, decentralised | centralised, decentralised |
| Special features | | | 2 independent drive controllers |
| | | | (SPD) in one housing |



Motors

Servo motors

Servo motors developed and manufctured by Parker Hannifin, offer an ideal solution for many applications. They are suitable for both highly-dynamic machines and applications requiring accurate synchronisation. All motors are designed using high-quality neodymium-iron-boron magnets. Special flanges and options offer increased flexibility, and all motors are designed with IP64 protection. These motors are notable for exceptional flexibility and wide power range.



Servomotors technical data (summary)

| | SMH/SMB/SME | MH/MB/ME |
|------------------------------|--|---|
| Continuous stall torque [Nm] | 0.2-19 | 0.2-126 |
| Peak torque [Nm] | 1.3-47 | 1.3-398 |
| Nominal Speed [rpm] | 1800-7500 | 550-10000 |
| Rotor inertia/ | 4-1400 | 11-14000 |
| Rotor [kgmm ²] | | |
| Flange sizes (selection) | 40x40 / 60x60 / 82x82 / 100x100 / | 56x56 / 70x70 / 105x105 |
| | 115x115 / 142x142 | 145x145 / 205x205 |
| Feedback | Resolver / Incr. Encoder / | Resolver / Incr. Encoder / |
| | Absol. Encoder/SinCos®, EnDat® | Absol. Encoder/SinCos®, EnDat® |
| Servo controller | SMH Compax3 | MH Compax3 |
| | SMB TBL/TBF, SLVD, ViX Servo, HiDrive, | MB TBL/TBF, SLVD, ViX Servo, HiDrive, |
| | SPD, TWIN | SPD, TWIN |
| | SME Aries, ViX Servo | ME Aries, ViX Servo |
| Options | Cable, plug, terminal box | Cable, plug, terminal box, Moment of inertia, |
| | Increased moment of inertia, holding brake | holding brake, passive cooling |
| Spezial features/ | Used in highly-dynamic and high | Used in highly-power usage |
| Usage | torque applications | |

Stepper motors

Parker Hannifin's stepper motors comply with NEMA standards 23 and 34, and are each available in three different stack lengths. These two-phase stepper motors are suitable for high-power applications and are used in combination with the ViX and XL stepper motor drives.

| SY |
|--|
| |
| 0.45-5.4 |
| 12.5-1200 |
| 56x56 / 86x86 / |
| NEMA23/NEMA34 in 1-3 stacks / NEMA42 in 2-3 stacks |
| ViX Stepper / XL / XLi |
| Cable / terminal box |
| |





Linear servo motor kits



| Туре | Ironless | Iron-cored | |
|----------------------|---|-----------------------------------|--|
| Continuous force [N] | 24 878 | 154 2230 | |
| Peak force [N] | 108 3928 | 587 7433 | |
| Cogging force | no | yes | |
| Power density | low/medium | high | |
| Attractive force | none | high | |
| Heat dissipation | - | ++ | |
| Applications | dynamic, precision, | Applications with high forces and | |
| | uniform motion | highly dynamic | |
| Maximum speed | depending on the mechanical guidance system | | |

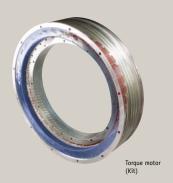


Torque motor kits

Typical characteristic features of a torque motor are low speed and high torque. Torque motors have a relatively high number of poles and are available with either solid or hollow shaft. The absence of a gearbox results in improved dynamic performance in rotary

applications. The torque motors ST and STK are used for rotary applications. As an alternative to convection cooling, forced air or water cooling is available.













Planetary gearboxes

A gearbox is necessary for many applications, and Parker Hannifin offers planetary gearboxes which are specifically adapted to electric drive technology. The gearboxes feature high efficiency, long service life and the ability to withstand high radial and axial forces at the shaft. Their noise emission is particularly low and all gearboxes are lifetime lubricated.

Depending on the applications, we can offer both economy gearboxes and precision planetary gearboxes with backlash less than 3 arc-minutes.

PTN:

Economy uniflange series

- Reduction ratio: 4:1, 8:1, 25:1
- Torque: 16Nm ...230Nm
- Flanges:
 - 60, 80, 115mm on the drive side
 - Uniflange on the motor side
- Input speed up to 4000min-1
- Efficiency up to 96% (4:1; 8:1) > 94% (25:1)

Precision

- Reduction ratio: 3:1 up to 100:1
- Torque: 50Nm up to 1100Nm
- Backlash:
 - 1 step < 4 arc-minutes
 - 2 step < 5 arc-minutes
 - available to < 1 arc-minutes
- Flanges: 60 ... 160mm
- Input speed up to 6000min-1
- Efficiency up to 97%
- Low-noise: <60db

All gearboxes can be modified to suit customer requirements.





Handling actuators

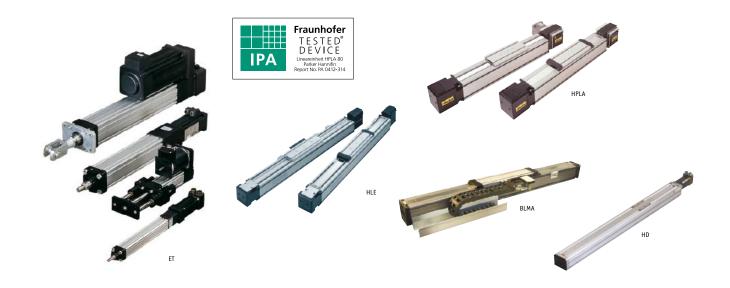
All linear actuators offered by Parker Hannifin feature a modular and therefore flexible structure. They reflect Parker's long practical experience in the field of handling technology. In addition, we have developed special solutions for various applications, such as actuators suitable for clean-room applications as well as actuators for the food industry. The mechanical components can be combined to create multi-axis systems with the aid of a range of attachments and accessories. The user can choose between different versions including linear, vertical and telescopic acutators as well as electric cylinders. In addition, several different drive technologies are available including ballscrews, toothed belt drive, linear motor and a combination of toothed belt and toothed rack.





| PowerRod | PRA. | PRC | technical data |
|----------|------|-----|----------------|

| | PRA | PRC | |
|----------------------------|------------------------------------|--------------|--|
| Profile/cross-section [mm] | Ø25/68*54 | Ø25/68*54 | |
| | Ø38/84*70 | Ø38/84*70 | |
| Drive Type | Linear motor | Linear motor | |
| Maximum stroke [mm] | 27 318 | up to 1362 | |
| Maximum speed [m/s] | 5.9 | 9.4 | |
| Maximum force [N] | 312 1860 | 312 1860 | |
| Stainless/food option | ✓ | ✓ | |
| Туре | Linear motor | Linear motor | |
| | Actuator | Components | |
| Feedback | Integrated length measuring system | | |



| Technical da | a (summary) |
|--------------|-------------|
|--------------|-------------|

| | ET | HLE/HPLA | BLMA | HD |
|-------------------------------|-------------------------|---------------------|---------------------|-------------------|
| Profile/cross-section [CETOP] | 32/50/80/100/125 | 80 180 [mm] | 120 [mm] | 85x70 185x95 [mm] |
| Drive Type | Screw | Toothed belt | Linear motor | Ballscrew |
| Guide mechanism | Rollers/sliding bearing | Rollers | Rollers | - |
| Maximum stroke [mm] | 50 2400 | 5610 9440 | 6329 | 100 1600 |
| Maximum speed [m/s] | 1 | 5 | 7 | 1.48 |
| Maximum force [N] | 600 44500 | 925 3700 | 310/1693 | 90 |
| Maximum load [kg] | - | 150 750 | 300 | 170 780 |
| Repeatability [mm] | ± 0.07/± 0.01 | <u>+</u> 0.2 | ± 0.01 | ± 0.008 |
| Clean room option | - | Yes | - | - |
| Stainless/food option | Yes | Yes | - | - |
| Туре | Electric cylinder | Toothed belt module | Linear motor module | Screw |



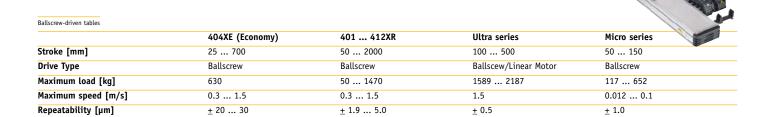
Technical data (summary)

| | HZR | HTR | LCB |
|----------------------------|-------------------|--------------------------------|---------------------|
| Profile/cross-section [mm] | 50/80/100 | 50/80 | 40/60 |
| Drive Type | Toothed belt | Toothed belt | Toothed belt |
| Guide mechanism | Rollers | Rollers | Sliding guide |
| Maximum load [kg] | 30/50/150 | 24/49 | 480/760 (static) |
| Maximum speed [m/s] | 5 | 5 | 8 |
| Maximum stroke [mm] | 1500/2000 | 3000/4000 | 2000/5500 |
| Repeatability [mm] | <u>+</u> 0.2 | <u>+</u> 0.2 | <u>+</u> 0.2 |
| Туре | Vertical actuator | Vertical actuator (telescopic) | Toothed belt module |

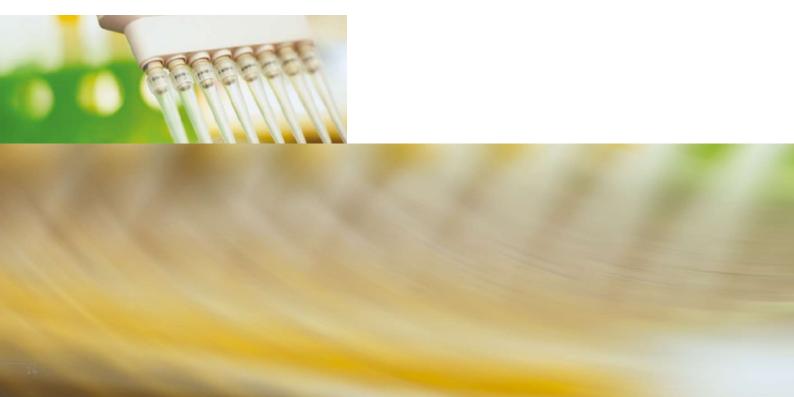
Precision actuators/tables

The precision tables and actuators are driven either by a ballscrew or by a linear motor. All mechanical components are optionally available for use in clean-room applications. The precision tables can be easily extended with corresponding accessories in order to build a complete X-Y or X-Y-Z system. All precision components are supplied with a performance certificate. Various options such as linear encoder systems, brakes, highly flexible cable sets and limit switches are available. The XR andLXR precision actuators achieve their high precision with

the aid of innovative ball bearing guides. The linear motor option helps both to increase the dynamic performance and to improve the precision. The XE "economy" version is compatible with the other products from the XR/LXR family.



| Linear motor driven tables | | | |
|----------------------------|--------------|------------------|------------------|
| | 404 412LXR | Trilogy Ironless | Trilogy Ironcore |
| Stroke [mm] | 50 3000 | 100 4200 | 100 3600 |
| Drive Type | Linear motor | Linear motor | Linear motor |
| Maximum load [mm] | 45 950 | 100 450 | 27 181 |
| Maximum speed [m/s] | 3.0 | 7 | 7 |
| Repeatability [µm] | 1 5 | 1 5 | 1 5 |



Miniature tables: MX80 and LX80L

The precision tables are available with different drive types including standard and high-precision ballscrews, linear motors and micrometer screws.

| | 7 |
|--|---|
| | |

| Technical data (summary) | | | | | | |
|----------------------------|------------|-----------|-----------|--------------|--------------|--------------|
| | MX80M | MX80SP | MX80SS | MX80LP | MX80LS | LX80L |
| Profile/cross-section [mm] | 80 x 25 | 80 x 35 | 80 x 35 | 80 x 25 | 80 x 25 | 80 x 45 |
| Material | Aluminium | Aluminium | Aluminium | Steel | Aluminium | Aluminium |
| Drive Type | Micrometer | Ballscrew | Ballscrew | Linear motor | Linear motor | Linear motor |
| Maximum stroke [mm] | 50 | 25 150 | 25 150 | 25 150 | 25 150 | 750 |
| Maximum speed [m/s] | - | 0.1 | 0.2 | up to 2 | up to 2 | 0.3 |
| Maximum force [N] | - | 123 | 44 | 12 | 12 | 10 |
| Maximum load [kg] | 20 | 8 | 8 | 8 | 8 | 10 |
| Repeatability [µm] | - | ± 1.5 | ± 5.0 | ± 0.4 | ± 0.8 | ± 1.5 |

Precision elevating table ZP200



ZP200 is a precision elevating table suitable for loads of up to 75kg. Like all precision products, the ZP200 is supplied with a test certificate and is optionally available for class 10 clean rooms.

| Technical data (summary) | | |
|----------------------------|------------|------------|
| | ZP200P | ZP200S |
| Profile/cross-section [mm] | 200 x 60,4 | 200 x 60,4 |
| Drive Type | Ballscrew | Ballscrew |
| Maximum stroke [mm] | 25 | 25 |
| Maximum speed [m/s] | 0.44 | 0.44 |
| Maximum load [kg] | 15 | 75 |
| Repeatability [µm] | ± 3.0 | ± 5.0 |

Rotary tables

| Technical data (summary) | | |
|--------------------------|--------------|------------|
| | DD Rotary | 200RT |
| Profile [mm] | 100 200 | 125 300 |
| Drive Type | Linear motor | Worm drive |
| Maximum speed [RPM] | 300 700 | 5 25 |
| Maximum torque [Nm] | 0.65 7.0 | 2.8 21.5 |
| Maximum load [kg] | 75 250 | 11 90 |
| Repeatability [arc/s] | ± 4.1 | 20 |









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